

An Exact Method for Assortment Optimization under the Nested Logit Model

Laurent Alfandari, Alborz Hassanzadeh, Ivana Ljubic

▶ To cite this version:

Laurent Alfandari, Alborz Hassanzadeh, Ivana Ljubic. An Exact Method for Assortment Optimization under the Nested Logit Model. 2020. hal-02463159v1

HAL Id: hal-02463159 https://essec.hal.science/hal-02463159v1

Preprint submitted on 31 Jan 2020 (v1), last revised 30 Mar 2021 (v2)

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

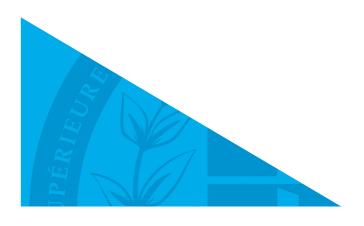


An Exact Method for Assortment Optimization under the Nested Logit Model

Laurent Alfandari Alborz Hassanzadeh Ivana Ljubic

ESSEC RESEARCH CENTER

WORKING PAPER 2001



An Exact Method for Assortment Optimization under the Nested Logit Model

Laurent Alfandari

ESSEC Business School, Cergy-Pontoise, France, alfandari@essec.edu

Alborz Hassanzadeh

ESSEC Business School, Cergy-Pontoise, France, al.zadeh@essec.edu

Ivana Ljubić

ESSEC Business School, Cergy-Pontoise, France, ivana.ljubic@essec.edu

Abstract

We study the problem of finding an optimal assortment of products maximizing the expected revenue, in which customer preferences are modeled using a Nested Logit choice model. This problem is known to be polynomially solvable in a specific case and NP-hard otherwise, with only approximation algorithms existing in the literature. For the NP-hard cases, we provide a general exact method that embeds a tailored Branch-and-Bound algorithm into a fractional programming framework. Contrary to the existing literature, in which assumptions are imposed on either the structure of nests or the combination and characteristics of products, no assumptions on the input data are imposed, and hence our approach can solve the most general problem setting. We show that the parameterized subproblem of the fractional programming scheme, which is a binary highly non-linear optimization problem, is decomposable by nests, which is a main advantage of the approach. To solve the subproblem for each nest, we propose a two-stage approach. In the first stage, we identify those products that are undoubtedly beneficial to offer, or not, which can significantly reduce the problem size. In the second stage, we design a tailored Branch-and-Bound algorithm with problem-specific upper bounds. Numerical results show that the approach is able to solve assortment instances with up to 5,000 products per nest. The most challenging instances for our approach are those in which the dissimilarity parameters of nests can be either less or greater than one.

Keywords: combinatorial optimization, revenue management, assortment optimization, fractional programming, nested logit.

1. Introduction

Assortment optimization is the problem of choosing a portfolio of products in a competitive environment to offer to customers to maximize expected revenue. This class of problems has important applications in retail, online advertising, or revenue management, see, e.g. [3, 18, 16]. The research of Talluri and Van Ryzin [27] was the first of its kind to demonstrate the importance of incorporating the choice behavior of customers when deciding which products to offer in an assortment. Their work contributes to the growing literature on discrete choice models. Such models have long been used to describe and understand how customers choose a product from an offered set of products that vary in different attributes such as price and quality. One prevailing assumption is that a customer purchases a fixed product in the system if that product is available, and if not, she leaves the system without a purchase. In reality, however, there might be several products that serve as substitutes and can satisfy customer's demand. As a result, researchers such as McFadden [22] established and developed random utility models, which led to the development of the Multinomial Logit (MNL) model. An extension of random utility models is the general nested attraction model of which Williams [28] first introduced a unique and valuable case that is the Nested Logit (NL) model.

In the NL model, customers first select a nest, and then choose a product within that nest. Since the multinomial logit model suffers from the assumption of independence of irrelevant alternatives, the nested logit model was developed to capture the degree of dissimilarity of products within a nest. This model has various applications. For example, consider a tourist who is using online search engines to book a hotel room. In this case, the nests are the available hotels to choose from, and a product is a room within each hotel. Naturally, the customer first selects a hotel and then selects a room from that hotel according to her preferences over the available options.

1.1. Problem definition

We first provide a formal definition of the Assortment Optimization Problem under the Nested-Logit choice model (AOPNL). Let $M = \{1, ..., m\}$ be the set of all nests, and $N = \{1, ..., n\}$ the set of all products. We call C_i the collection of all feasible assortments for nest $i \in M$, and an assortment in nest i is denoted by $S_i \in C_i$. We also denote by $r_{ik} \ge 0$ the revenue obtained by selling one unit of product $k \in S_i$ offered in nest i. Finally, customers' preference for product k in nest i is v_{ik} .

Assuming a customer chooses nest i and assortment $S_i \in \mathcal{C}_i$ is offered for nest i, the probability for that customer to choose product k is:

$$P_{ik}(S_i) = \begin{cases} \frac{v_{ik}}{v_{i0} + \sum_{k \in S_i} v_{ik}} & k \in S_i \\ 0 & k \notin S_i \end{cases} \qquad i \in M, k \in N$$
 (1)

where v_{i0} is the attractiveness of leaving nest i without any purchase. Furthermore, the probability that a particular nest i is chosen given that assortment $(S_1, \ldots, S_m) \in \mathcal{C}_1 \times \ldots \times \mathcal{C}_m$ is offered is:

$$Q_i(S_1, \dots, S_m) = \frac{(v_{i0} + \sum_{k \in S_i} v_{ik})^{\gamma_i}}{V_0 + \sum_{l \in M} (v_{l0} + \sum_{k \in S_l} v_{lk})^{\gamma_l}} \qquad i \in M$$

where V_0 is the attractiveness of the option of leaving the system without purchasing anything, and γ_i is the dissimilarity parameter of a nest. The dissimilarity parameter of a nest characterizes the degree of dissimilarity between the products within that nest. It can also be interpreted as the influence of a nest over others [11, 15]. Finally, the assortment optimization problem where customer choice behavior follows a nested logit model is to find an optimal assortment within each nest, so that the expected revenue is maximized, i.e., we have:

$$Z = \max_{\substack{(S_1, \dots, S_m) \\ S_i \in \mathcal{C}_i, i \in M}} \Pi(S_1, \dots, S_m) = \max_{\substack{(S_1, \dots, S_m) \\ S_i \in \mathcal{C}_i, i \in M}} \sum_{i \in M} Q_i(S_1, \dots, S_m) \sum_{k=1}^n P_{ik}(S_i) r_{ik}$$

The authors of [9] proved that unless $\gamma_i \leq 1$ and $v_{i0} = 0$ for all $i \in M$, problem (2) is NP-hard. In this article, we provide an exact solution framework for solving the AOPNL in a general setting, even when $\gamma_i > 1$ or $v_{i0} > 0$, for some $i \in M$.

1.2. Motivation and main contribution

The literature of assortment optimization under the nested logit model is quite rich concerning analytical properties of the problem under various assumptions. For example, one primary assumption is that the dissimilarity parameter of all nests is less than or equal to one (which means that all products within the same nest compete against each other). This assumption might be easily violated since some products might act synergistically. This situation has been thoroughly explained in the research of Davis et al. [9]. Their work is the only available paper that studies scenarios in which dissimilarity parameters can be higher than one, and for that, the authors proposed a heuristic algorithm that provides assortments with a worst-case performance guarantee. Similarly, in the detailed research of Gallego and Topaloglu [15] and Feldman and Topaloglu [13], the dissimilarity parameter is assumed to be less than or equal to one, and if there is a capacity constraint, the authors propose an approximation algorithm.

In this paper we provide an exact method based on fractional-programming, to generate optimal assortments under the nested logit model. Contrary to the existing literature, our method can be used to solve a wide range of problem variants as it imposes no assumption on the input data. The key point of the method is that the parameterized subproblem at each iteration of the main fractional programming algorithm, which is a highly non-linear binary optimization problem, can be decomposed by nest. This enables to solve a collection of subproblems that are relatively easier to handle.

Each subproblem for each nest is solved in two phases. First, a pre-processing enables to reduce the size of the subproblem by identifying revenue thresholds beyond which products are sure to be offered or not. Then a Branch-and-Bound (B&B) algorithm solves the reduced problem, using both pre-processing and tailored upper bounds at each node. To the best of our knowledge, this research is the first to provide a generic exact method for the assortment

optimization problem under the nested logit model with proven optimality, which is flexible enough to adapt to any mix of dissimilarity parameters and any mix of utilities of no-purchase options. Moreover, our method is effective for instances of realistic size involving thousands of products, for which optimal assortments can be computed within short computing time.

The paper is organized as follows. In the remainder of this section, we provide a detailed literature overview. The general framework of our parametric search and the decomposition of the parameterized subproblem by nests are explained in Section 2. In Section 3, the parameterized subproblem is analyzed with the identification of the products that are sure to be offered or not at optimality, based on revenues, and the branch-and-bound algorithm for solving the reduced problem is provided. Section 4 is dedicated to numerical experiments to assess the performance of the method on many instances of various sizes, and we conclude our research in Section 5.

1.3. Related literature

The incorporation of choice models in assortment optimization problems (AOP) has attracted much attention in the recent decade. One of the most popular discrete choice models is the multinomial logit model. Since Talluri and Van Ryzin [27] demonstrated that under the multinomial logit model, offering revenue-ordered assortments maximizes the expected revenue, many researchers studied this class of problem with various assumptions. For example, Flores et al. [14] demonstrated that offering revenue-ordered assortments provides the optimal solution if consumers' choice model follows a sequential multinomial logit which is a generalized version of the classic MNL. In the context of robust optimization, Rusmevichientong and Topaloglu [24] demonstrated that even if the utilities of products are unknown yet belong to some uncertainty set, the revenue-sorted assortments still provide maximum expected revenue.

The multinomial logit model was developed based on two main assumptions; 1) customers follow the utility maximization principle, and 2) the utilities of products are independent of each other. In real-world conditions, however, the second assumption might be violated. To remedy this potential shortcoming of MNL, researchers developed other utility-maximizing models such as the Nested Logit model by Williams [28]. Detailed justifications of this model are available in these extensive research [6, 2, 21]. We focus our literature review on the research that primarily uses variants of the nested logit model to incorporate the customer choice process in the assortment optimization problem. The available literature is rich and shows how active this area of research is.

In Table 1, we classify the literature on the AOP under the nested logit model based on the value of the dissimilarity parameter of each nest, and whether the proposed method provides an optimal solution or an approximation. We also classify those papers based on the integration of pricing decisions in AOP. For example, Li and Rusmevichientong [19] developed a greedy algorithm to solve the AOP in polynomial time. They assume that the nest dissimilarity parameter is less than or equal to one for all nests. In another class of AOP under nested logit, Gallego and Topaloglu [15] imposed capacity and cardinality constraints on each nest. They show that under cardinality constraint, it is possible to get an optimal assortment by reducing the AOP to a knapsack problem. When having space or capacity constraints, however, they show how to come up with a combination of products as a candidate assortment for each nest to have a worst-case guarantee. One primary assumption in their research is that the constraint is imposed for each nest separately.

To relax this assumption, Feldman and Topaloglu [13] considered a similar problem when there is a cardinality or capacity constraint over all nests. They show that when each product consumes one unit of space, the problem can be solved to optimality using an algorithm that sequentially solves a linear and dynamic program. This approach cannot be used if we have a capacity constraint across all nests, and for that case, they provide an approximation solution with a worst-case performance guarantee. In a different context, Davis et al. [10] studied a pricing problem where customers' choice is a nested logit model and there is a relation between product quality and its price which they call quality consistency constraint. For this problem, they developed a polynomial time algorithm with proven optimality.

Chen and Jiang [8] incorporated the problem of product pricing in the context of assortment optimization under d-level nested logit. They also impose cardinality and capacity constraints and show that when having capacity limits, using their approximation scheme, one can come up with an assortment that guarantees a fixed performance, and for the case with cardinality constraint, they develop an algorithm that solves the problem to optimality in polynomial time. Focusing only on a capacity constraint, Désir et al. [11] developed a fully polynomial-time algorithm to provide an approximation scheme for the assortment optimization problem under various choice models, including nested logit. A more generic model of the nested logit choice is studied combined with a pricing problem in the research of Li et al. [20] where they consider a nest logit tree with more than two levels.

In their thorough research, Davis et al. [9] studied the same version of the AOP with the nested logit model which is the focus of our manuscript. They divide their work based on whether nest dissimilarity parameters are below one or not, and whether the no-purchase option exists for each nest or not. They proved that if in all nests, products compete with each other and if there is no option of leaving the nest without a purchase, either the optimal assortment is an empty set, or it has sorted-by-revenue products. They prove that if dissimilarity is less than 1 for all the nests and customers can leave a nest without purchasing anything, their heuristic has a worst-case performance guarantee of 2 and if the dissimilarity parameter is free, if customer cannot leave a nest without a purchase, offering sorted-by-revenue assortments in each nest, we can get a worst-case performance guarantee of $\max\{\rho, 2\kappa\}$. Here κ bounds the ratio between the largest and the smallest preference parameters in a nest, i.e., $\kappa = \max_{i \in M} \{\frac{\max_{k \in N} v_{ik}}{\min_{k \in N} v_{ik}}\}$, and $\rho = \max_{i \in M} \{\frac{\max_{k \in N} r_{ik}}{\min_{k \in N} r_{ik}}\}$. Finally, for the most general case with dissimilarity parameters being free and customers having the no-purchase option, the approach of Davis et al. [9] provides a performance grantee of 2κ . Regarding the complexity of the problem, the authors also show that if the customers have the no-purchase option or if the nest dissimilarity parameter is greater than one, the AOPNL is NP-hard. This complexity

motivated our research.

In a different context, Goyal et al. [16] considered a problem where the quality of different products is similar and customers differentiate products based on their price. Therefore, customers' preferences have a form of nested lists which means products are ordered by increasing selling price per unit and customers always prefer the cheapest product. This model is called the nested preference list choice model. Each preference list is based on a different price threshold. A particular customer that has a preference list is willing to purchase all the products with price lower than its threshold. For this problem, the authors devised an approximation scheme. They also developed polynomial-time approximations for this problem under specific choice models.

Since their model has restricting assumptions, Segev [25] considered the most general form of nested preference list choice model in AOP and developed a dynamic programming scheme to provide an approximated solution for this problem. And finally, Çetin e al. [7] adapted the concept of choice models to determine the optimal promotional display within a brick-and-mortar store. They reason that the customer first is faced with the promotional display (if any) and chooses whether to purchase the promoted product, visit the category's aisle location, or even leave without purchasing anything from the nest (product category).

Table 1: An overview of research on assortment planning under nested logit

		$\gamma \in [0, 1]$		γ free
Solution	-	Cardinality cons.	Capacity cons.	
Exact	[9, 19]	[15, 13, 8]		
Approx.	[9]		[15, 13, 11, 8]	[9]

2. Fractional programming approach

Recall from the previous section, the assortment optimization problem when customers' choice model follows a nested logit can be written as:

$$Z = \max_{\substack{(S_1, \dots, S_m) \\ S_i \in C_i, i \in M}} \Pi(S_1, \dots, S_m) \quad \text{where}$$

$$\Pi(S_1, \dots, S_m) = \sum_{i \in M} Q_i(S_1, \dots, S_m) \sum_{k=1}^n P_{ik}(S_i) r_{ik}$$

$$= \sum_{i \in M} \frac{(v_{i0} + \sum_{k \in S_i} v_{ik})^{\gamma_i}}{V_0 + \sum_{l \in M} (v_{l0} + \sum_{k \in S_l} v_{lk})^{\gamma_l}} \times \frac{\sum_{k \in S_i} r_{ik} v_{ik}}{v_{i0} + \sum_{k \in S_i} v_{ik}}$$

$$= \frac{\sum_{i \in M} (v_{i0} + \sum_{k \in S_i} v_{ik})^{\gamma_{i-1}} \sum_{k \in S_i} r_{ik} v_{ik}}{V_0 + \sum_{i \in M} (v_{i0} + \sum_{k \in S_i} v_{ik})^{\gamma_i}}$$

$$(2)$$

2.1. Problem reformulation

Assume we can enumerate all the 2^n subsets (possible assortments) in each collection C_i , for $i \in M$. Let x_{S_i} be a binary variable which is set to one if and only if we offer assortment $S_i \in C_i$. Then AOPNL can be rewritten as the following binary non-linear program with an exponential number of binary variables:

$$\max \frac{\sum_{i \in M} \sum_{S_{i} \in C_{i}} \left((v_{i0} + \sum_{k \in S_{i}} v_{ik})^{\gamma_{i} - 1} \sum_{k \in S_{i}} r_{ik} v_{ik} \right) x_{S_{i}}}{V_{0} + \sum_{i \in M} \sum_{S_{i} \in C_{i}} \left((v_{i0} + \sum_{k \in S_{i}} v_{ik})^{\gamma_{i}} \right) x_{S_{i}}} = \frac{N(x)}{D(x)}$$
s.t:
$$\sum_{S_{i} \in C_{i}} x_{S_{i}} = 1 \qquad i \in M$$

$$x_{S_{i}} \in \{0, 1\}, \qquad S_{i} \in C_{i}, i \in M$$

Observe that if $S_i \in \mathcal{C}_i$, for all $i \in M$ are explicitly generated, then the expressions before variables x_{S_i} in the nominator N(x) and denominator D(x) of (3) are constant coefficients, and so the problem boils down to a binary fractional program in variables x_{S_i} . Integer fractional programming is a powerful modeling tool which has been successfully applied to a wide range of applications including landscape ecology and forest fragmentation [4], biodiversity conservation [5], inventory routing [1], portfolio optimization and wind-farm optimization [26], or network optimization [17].

Following Dinkelbach [12], Megiddo [23] proposed a method to solve fractional programs with 0-1 variables. The idea is to iteratively solve a so-called parameterized problem $F_{par}(\lambda) = N(x) - \lambda D(x)$ until $N(x) - \lambda D(x) = 0$ (in practice, $|N(x) - \lambda D(x)| \le \epsilon$ where ϵ is a very small positive real number). Then the λ^* found is the optimal ratio, and x^* is the vector optimizing the ratio, i.e.,

$$\max_{x} \left\{ \frac{N(x)}{D(x)} \right\} = \frac{N(x^*)}{D(x^*)} = \lambda^*$$

For the AOPNL, the corresponding iterative parameterized problem $F_{par}(\lambda)$ is:

$$F_{par}(\lambda): \max_{\substack{(S_1, \dots, S_m) \\ S_i \in \mathcal{C}_i, i \in M}} \sum_{i \in M} \left((v_{i0} + \sum_{k \in S_i} v_{ik})^{\gamma_i - 1} \sum_{k \in S_i} r_{ik} v_{ik} \right) - \lambda \left(V_0 + \sum_{i \in M} (v_{i0} + \sum_{k \in S_i} v_{ik})^{\gamma_i} \right)$$
(4)

The following theorem follows from the findings in [23].

Theorem 1. If one can find a λ^* for which $F_{par}(\lambda^*) = 0$ and solves problem (4) with $\lambda = \lambda^*$, then the collection of assortments $(S_1(\lambda^*), ..., S_m(\lambda^*))$ is the optimal solution to problem (3) and $Z^* = \lambda^*$.

We now show that the above parameterized problem is decomposable by nest.

2.2. Decomposability of the parameterized subproblem

Proposition 1. The parameterized problem (4) is separable by nest and can be written as:

$$F_{par}(\lambda): -\lambda V_0 + \sum_{i \in M} \max \left\{ (v_{i0} + \sum_{k \in N} v_{ik} x_{ik})^{\gamma_i - 1} (\sum_{k \in N} v_{ik} (r_{ik} - \lambda) x_{ik} - \lambda v_{i0}) \right\}$$
s.t: $x_{ik} \in \{0, 1\}, k \in N, i \in M$

where x_{ik} are binary variables that are set to one if and only if product $k \in N$ is offered in nest $i \in M$.

Proof. Since in problem (4) we have simple assignment constraints of choosing one assortment per nest, we observe that the objective of the parameterized program can be rewritten as:

$$-\lambda V_0 + \sum_{i \in M} \max_{S_i \in \mathcal{S}_i} \left\{ \left(v_{i0} + \sum_{k \in S_i} v_{ik} \right)^{\gamma_i - 1} \left(\sum_{k \in S_i} v_{ik} (r_{ik} - \lambda) - \lambda v_{i0} \right) \right\}.$$

Hence, the program is $decomposable\ by\ nest$, and the maximization subproblem for nest i is given as:

$$\max_{S_i \in \mathcal{C}_i} \left\{ (v_{i0} + \sum_{k \in S_i} v_{ik})^{\gamma_i - 1} \left(\sum_{k \in S_i} v_{ik} (r_{ik} - \lambda) - \lambda v_{i0} \right) \right\}$$
 (6)

We can see the above problem as a binary non-linear program with decision variables x_{ik} indicating whether product $k \in N$ is offered in nest $i \in M$, and so the whole problem can be reformulated like in (5).

This result enables to speed up the resolution of the subproblem by solving a smaller problem for each nest $i \in M$. To find the optimal value of λ , we use the framework proposed by [23] that is illustrated in Algorithm 1. The algorithm is a dichotomic search on λ based on the fact that function $F_{par}(\lambda)$ in (5) is piece-wise linear in λ . We refer the reader to [23, 12] for further details on the algorithm and its proven convergence to optimality.

2.3. Algorithmic details

To initialize our parametric search, we first need to determine a lower bound λ_l and an upper bound λ_u for λ^* . The value of λ_l corresponds to a primal bound of the AOPNL that can be obtained by applying a heuristic approach. We choose to set the initial value of λ_l by running the heuristic proposed by [9] in which λ_l corresponds to the maximum expected revenue obtained by offering sorted-by-revenue assortments, which is known to be the optimal value of the following linear program (see [9]):

$$\lambda_l = \min \quad \lambda \tag{7}$$

$$\lambda_l = \min_{\text{s.t.}} \lambda$$

$$\text{s.t.} V_0 \lambda \geqslant \sum_{i \in M} y_i$$
(8)

$$y_i \geqslant V(N_{ik})^{\gamma_i}(R(N_{ik}) - \lambda), \quad i \in M, k \in N$$
 (9)

where $N_{ik} = \{1, \dots, k\}$, for $k \in N$, is the subset of k best-revenue products for nest $i \in M$ (sorted-by-revenue assortments), $V(N_{ik}) = v_{i0} + \sum_{k \in N_{ik}} v_{ik}$ and $R(N_{ik}) = \sum_{k \in N_{ik}} r_{ik} v_{ik} / V(N_{ik})$.

Observe that in the expression of $\Pi(S_1,\ldots,S_m)$ at the second line of (2), probabilities Q_i and P_{ik} sum over at most one (less than one if V_0 and v_{i0} are positive). Therefore, Z is bounded above by some linear combination of revenues r_{ik} with weights summing over one, which is at most the highest revenue. Therefore, we set

$$\lambda_u = \max\{r_{ik} : k \in N, i \in M\}.$$

We notice that in [9], the authors propose a much tighter upper bound for the AOPNL, which is based on solving a continuous relaxation of the problem reformulation. The latter boils down to a convex semi-infinite program which is solved using a cutting plane approach, based on outer approximation. Calculation of this bound is computationally too expensive, which is why we stick to a simple bound that can be precomputed in the initialization phase.

Moreover, in the following proposition, we provide an additional stopping criterion that speeds up the dichotomic search (see, e.g., [17]).

Proposition 2. At any iteration of the dichotomic search, let $S_l(\lambda_l)$ and $S_u(\lambda_u)$ be the optimal assortments found for $F_{par}(\lambda_l)$ and $F_{par}(\lambda_u)$, respectively. If $S_l(\lambda_l) = S_u(\lambda_u)$, then $S^* = S_l(\lambda_l) = S_u(\lambda_u)$ is the optimal assortment for the original problem.

Proof. See Appendix.
$$\Box$$

In the pretests, the above criterion was shown to be an effective measure to reduce the processing time of the developed parametric search. We summarize the steps of the developed parametric search in Algorithm 1. We start by initializing the values for λ_u and λ_l as described above. The function "Solve $F_{par}(\lambda)$ ", called in Step 8 returns the optimal assortment S^* over all subproblems with respect to parametric objective function value given in (4), and the optimal solution value F^* . Upon calling this function, |M| subproblems are solved independently, according to Proposition 1. As we will show later, each subproblem is NP-hard. For that reason, we provide a detailed analysis of the subproblem and develop an exact branch-and-bound method to solve it. If the time limit is reached, our framework returns the best incumbent solution S_{best} as well as a tight upper bound λ_u which can be used to measure the quality of S_{best} .

Algorithm 1: Parametric search for solving the AOPNL

```
Data: Instance of the AOPNL problem, time limit TL
     Result: Optimal or best found (if TL is reached) solution S_{best}. The upper bound \lambda_u.
     Initialize (\lambda_l, \lambda_u);
     S_l \leftarrow \text{Optimal assortment from solving (7)-(9)};
 S_u \leftarrow \emptyset;
 4 S_{best} = S_l;
     while |F^*| > \epsilon and S_l \neq S_u and TL is not reached do
            \lambda \leftarrow (\lambda_l + \lambda_u)/2;
            (F^*, S^*) \leftarrow \text{Solve } F_{par}(\lambda);
            if \Pi(S^*) > \Pi(S_{best}) then
 9
              |S_{best} \leftarrow S^*
10
            if F_{par}(\lambda) < 0 then
11
                \lambda_u \leftarrow \lambda, \, S_u \leftarrow S^*;
12
13
              | \lambda_l \leftarrow \lambda, \, S_l \leftarrow S^*;
15 return (S_{best}, \lambda_u);
```

3. Subproblem analysis and branch-and-bound

In the previous sections, we showed how implementing a fractional programming framework enables to deal with one nest at a time. In other words, instead of considering the original assortment optimization problem (2) with all nests, we can focus on providing the optimal assortment for each nest with a different objective function that is derived from the parametric function (5). We dedicate this section to study and analyze the properties of the resulting subproblem. We observe that removing the constant term λV_0 from formulation (5) does not change the optimal solution, and throughout this section, we drop index i and refer to the following problem as the subproblem of the parametric search algorithm, that we denote by (NLAPP) for the Nested-Logit Assortment Parameterized Problem:

(NLAPP)
$$\max_{x \in \{0,1\}^{|N|}} \left\{ (v_0 + \sum_{k \in N} v_k x_k)^{\gamma - 1} (\sum_{k \in N} v_k (r_k - \lambda) x_k - \lambda v_0) \right\}$$
 (10)

where x_k is a binary decision variable on whether to offer product k in the given nest or not. We first show NP-hardness of that problem, then we describe the revenue thresholds for fixing variables and the branch-and-bound algorithm.

Proposition 3. The subproblem (NLAPP) is NP-hard for any $\gamma > 1$.

Proof. We reduce the NP-complete Subset-Sum decision problem to our nested-logit parameterized subproblem (NLAPP) with arbitrary values of $\gamma > 1$ and $\lambda \ge 1$.

The Subset-Sum decision problem (SSP) is described as follows. Given n integer numbers a_1, \ldots, a_n and an integer number $B < \sum_{k=1}^n a_k$, is there a subset $S \subset \{1, \ldots, n\}$ such that $\sum_{k \in S} a_k = B$?

We reduce a general instance of (SSP) to a specific (NLAPP) as follows. Set v_0 at some arbitrary value less than B. Set $N = \{1, \ldots, n, n+1\}$, $v_k = a_k$ and $r_k = \lambda - 1$ for $k = 1, \ldots, n$. Moreover, set $v_{n+1} = B - v_0$ and

$$r_{n+1} = \lambda + \frac{B\left(\frac{\gamma+1}{\gamma-1}\right) + \lambda v_0}{v_{n+1}},$$

and

$$C_1 = v_{n+1}(r_{n+1} - \lambda) - \lambda v_0 = B\left(\frac{\gamma + 1}{\gamma - 1}\right).$$

As $C_1 > 0$ and $r_{n+1} > \lambda$, product n+1 will be offered for sure in the optimal solution (see Proposition 7), i.e., $x_{n+1}^* = 1$, and after denoting $V_1 = v_0 + v_{n+1} = B$, the subproblem reduces to the following problem (Q):

$$(Q) \max_{x \in \{0,1\}^n} f(x) = \left(V_1 + \sum_{k=1}^n v_k x_k\right)^{\gamma - 1} \times \left(C_1 + \sum_{k=1}^n v_k (r_k - \lambda) x_k\right)$$
(11)

We show that if we can find a solution of (Q) with value at least $\frac{(2B)^{\gamma}}{\gamma-1}$, then the answer to the subset-sum decision problem is yes, i.e., there exists a subset $S \subset \{1, \ldots, n\}$ such that $\sum_{k \in S} a_k = B$. Observe that with the above setting, our (NLAPP) instance can be rewritten as:

$$\max_{x \in \{0,1\}^n} f(x) = \left(V_1 + \sum_{k=1}^n a_k x_k\right)^{\gamma - 1} \times \left(C_1 - \sum_{k=1}^n a_k x_k\right)$$
$$= \left(V_1 + g(x)\right)^{\gamma - 1} \times \left(C_1 - g(x)\right) \quad \text{with } g(x) = \sum_{k=1}^n a_k x_k.$$

Now define function $h(X) = (V_1 + X)^{\gamma - 1} \times (C_1 - X)$ over $[0, C_1]$, such that h(g(x)) = f(x). Observe that without loss of generality we can focus on the interval $[0, C_1]$, since for $X > C_1$ we have h(X) < 0. We have

$$h'(X) = (C_1 - X)(\gamma - 1)(V_1 + X)^{\gamma - 2} - (V_1 + X)^{\gamma - 1}$$

$$= (V_1 + X)^{\gamma - 1} \left(\frac{(C_1 - X)(\gamma - 1)}{V_1 + X} - 1\right)$$

$$= 0 \text{ iff } X = C_1 \frac{\gamma - 1}{\gamma} - \frac{V_1}{\gamma} = B$$

Since $h(C_1) = 0$, and

$$h(B) = (2B)^{\gamma - 1} \times \left(B\left(\frac{\gamma + 1}{\gamma - 1}\right) - B \right) = 2^{\gamma - 1} B^{\gamma} \left(\frac{2}{\gamma - 1}\right) = \frac{(2B)^{\gamma}}{\gamma - 1} > 0$$

then X = B is a maximum for function h. We conclude that if a solution of (Q) reaches value $\frac{(2B)^{\gamma}}{\gamma-1}$ then there exists $x \in \{0,1\}^n$ such that $g(x) = \sum_{k=1}^n a_k x_k = B$ which is a solution for the Subset-Sum decision problem. Since the latter is NP-complete and the reduction described above is a polynomial reduction, this completes the NP-completeness proof for the decision version of (NLAPP).

We now describe the Branch-and-Bound (B&B) algorithm. We classify our analysis based on the value of the dissimilarity parameter of a nest and consequently, the properties of the subproblem for a nest i change according to the value of γ_i .

3.1. A tailored Branch-and-Bound algorithm

Subproblem (10) can be solved by off-the-shelf MINLP solvers for reasonable sizes of |N|. However, when the number of products increases, generic solvers are inefficient. Therefore, we develop a tailored B&B algorithm to determine the optimal assortment for each nest. We have a set of variables that have been fixed to 1 throughout the B&B tree until node t. We denote this set by K_1^{t-1} . We also have a set of variables that have been fixed to 0. We use K_0^{t-1} to denote this set. Finally, we have a set of undecided variables denoted by \bar{K}^{t-1} . We define

$$C_1^{t-1} = \sum_{j \in K_1^{t-1}} v_j(r_j - \lambda) - \lambda v_0$$

as the sum of the weighted revenue of products offered in a particular nest. We also define

$$V_1^{t-1} = \sum_{j \in K_1^{t-1}} v_j + v_0 \tag{12}$$

as the sum of preferences for the respective products. Using these notations, at each node t in the B&B tree, the objective function to be maximized is:

$$\max_{x \in \{0,1\}^{|\bar{K}^{t-1}|}} f^t(x) = \left(V_1^{t-1} + \sum_{k \in \bar{K}^{t-1}} v_k x_k \right)^{\gamma - 1} \times \left(C_1^{t-1} + \sum_{k \in \bar{K}^{t-1}} v_k (r_k - \lambda) x_k \right)$$
(13)

We naturally branch on binary variable $x_k \in \bar{K}^{t-1}$ fixing $x_k = 1$ and $x_k = 0$ in the two child nodes of a node t of the tree. In the branching ordering, priority is given to variables x_k with highest revenue r_k , with child node $x_k = 1$. The main issue is how to estimate an upper bound on the objective value of a node, say t, that is both i) tight enough to enable efficient pruning, and ii) tractable enough to be quickly computed, despite the non-linearity of the objective. Observe that the structure of the subproblem varies with the value of the nest dissimilarity parameter γ , considering two main cases: $\gamma \leq 1$ and $\gamma > 1$.

It turns out that the subproblem has interesting characteristics that allow to perform a preprocessing procedure and eliminate some of the variables without branching, which in turn speeds up the computation time. We update sets \bar{K}^{t-1} , K_0^{t-1} and K_1^{t-1} and constants C_1^{t-1} and V_1^{t-1} by removing or adding variables that were fixed either by branching or the preprocessing. In the next sections, we provide detailed descriptions of this preprocessing procedure and upper bound calculations, for each case $\gamma \leq 1$ and $\gamma > 1$.

3.2. Competitive products ($\gamma \leq 1$)

We identify three possible scenarios at the root node. For each scenario, we derive some measures to perform a preprocessing and potentially fix a relatively large number of variables before entering the B&B tree. We first observe that if $\gamma \leq 1$, we can reformulate the objective function (10) at the root node 0 as:

$$\max_{x \in \{0,1\}^{|N|}} f^0(x) = \left\{ \frac{\sum_{k \in N} v_k(r_k - \lambda)x_k - \lambda v_0}{(v_0 + \sum_{k \in N} v_k x_k)^{1-\gamma}} \right\}$$
(14)

and we proceed to the following proposition.

Proposition 4. At the root node (t = 0), set $\mathcal{H} = \sum_{k \in N: r_k \geqslant \lambda} v_k(r_k - \lambda) - \lambda v_0$. We have three possible scenarios based on the value of \mathcal{H} :

i) if $\mathcal{H}=0$ (Case 0), the problem is solved by preprocessing without branching; defining $K_1^0=\{k\in N: r_k\geqslant \lambda\}$ and $K_0^0=\{k\in N: r_k<\lambda\}$, the optimal solution of the subproblem is $x_k^*=1$ for $k\in K_1^0$ and $x_k^*=0$ for $k\in K_0^0$.

ii) if $\mathcal{H} > 0$ (Case 1), let $K_0^0 = \{k \in N : r_k < \lambda\}$, then $x_k^* = 0$ for $k \in K_0^0$. Moreover, define $K' = N \setminus K_0^0$ and $r_{max} = \max_{j \in N} \{r_j\}$ and let $K_1^0 = \{k \in N \setminus K_0^0 : r_k \geqslant \lambda + (1 - \gamma)(r_{max} - \lambda - (v_0 r_{max})/(v_0 + \sum_{j \in K'} v_j))\}$, then $x_k^* = 1$ for $k \in K_1^0$.

iii) if $\mathcal{H} < 0$, (Case 2) let $K_1^0 = \{k \in N : r_k \geqslant \lambda\}$, then $x_k^* = 1$ for $k \in K_1^0$. Moreover, we define $K' = N \setminus K_1^0$, $r_{min} = \min_{j \in K'} \{r_j\}$, and $\Delta = C_1^0 - V_1^0(r_{min} - \lambda)$, then we have two cases:

• If
$$\Delta \geqslant 0$$
, $x_k^* = 0$ for $k \in K_0^0 = \left\{ k \in K' : r_k \leqslant \lambda + (1 - \gamma) \left(\frac{C_1^0 + (r_{min} - \lambda) \sum_{j \in K'} v_j}{V_1^0 + \sum_{j \in K'} v_j} \right) \right\}$

• If
$$\Delta < 0$$
, then $x_k^* = 0$ for $k \in K_0^0 = \{k \in K' : r_k \leqslant \lambda + (1 - \gamma)(C_1^0/V_1^0)\}$

Proof. See Appendix.
$$\Box$$

The findings of the above proposition are crucial for the preprocessing of nodes other than the root node. It is trivial that if $\mathcal{H}=0$ at the root node, we prune the root node and the optimal assortment is found for the nest. While this is theoretically possible, this scenario is found to be quite rare in the numerical experiments. Remark that if $\mathcal{H}>0$, after performing the pre-processing of Proposition (4) we have $r_k \geq \lambda$ at any other node of the B&B tree. On the other hand, if $\mathcal{H}<0$ we have $r_k<\lambda$ for the remaining undecided variables at any node t.

These findings are the result of the structure of the tree and follow from the proof of Proposition (4) and the fact that in Case 1, where $\mathcal{H} > 0$, there exists a combination of products that realizes a positive value for the objective function (10). This means that after fixing all the variables with $r_k < \lambda$ to zero at the root node, it is not beneficial to add any of these variables to the optimal assortment of a nest at any other node since doing so would provide an objective value that is less than the one at the root node which is in contradiction with the maximization of the objective function. We can follow a similar logic for Case 2.

Proposition 5. At any node $t \neq 0$, depending on the value of \mathcal{H} calculated at the root node, we can have one of the two following scenarios:

$$\begin{array}{l} i) \ \ if \ \mathcal{H} \ > \ 0 \ \ (\text{Case 1}), \ set \ r_{max} \ = \ \max_{j \in \bar{K}^{t-1}} \{r_j\} \ \ and \ \ define \ K_1^t \ = \ \Big\{k \in \bar{K}^{t-1} \ : \ r_k \ \geqslant \\ \lambda + (1-\gamma) \left(\frac{C_1^{t-1} + (r_{max} - \lambda) \sum_{j \in \bar{K}^{t-1}} v_j}{V_1^{t-1} + \sum_{j \in \bar{K}^{t-1}} v_j}\right) \Big\}. \ \ Then \ x_k^* = 1 \ for \ k \in K_1^t. \end{array}$$

ii) if $\mathcal{H} < 0$ (Case 2), we define $r_{min} = \min_{j \in \bar{K}^{t-1}} \{r_j\}$ and $\Delta = C_1^{t-1} - V_1^{t-1}(r_{min} - \lambda)$, then we have two cases:

$$\bullet \ \ \textit{If} \ \Delta \geqslant 0, \ x_k^* = 0 \ \textit{for} \ k \in K_0^t = \left\{ k \in \bar{K}^{t-1} : r_k \leqslant \lambda + (1-\gamma) \left(\frac{C_1^{t-1} + (r_{min} - \lambda) \sum_{j \in \bar{K}^{t-1}} v_j}{V_1^{t-1} + \sum_{j \in \bar{K}^{t-1}} v_j} \right) \right\}$$

• If
$$\Delta < 0$$
, then $x_k^* = 0$ for $k \in K_0^t = \{k \in \bar{K}^{t-1} : r_k \leqslant \lambda + (1 - \gamma) \left(C_1^{t-1}/V_1^{t-1}\right)\}$

Proof. See Appendix.
$$\Box$$

After fixing variables using the above revenue thresholds, we restrict the set of undecided variables to \bar{K}^t and at each node t after preprocessing, the subproblem will reduce to:

$$\max_{x \in \{0,1\}^{|\bar{K}^t|}} f^t(x) = \left(V_1^t + \sum_{k \in \bar{K}^t} v_k x_k \right)^{\gamma - 1} \times \left(C_1^t + \sum_{k \in \bar{K}^t} v_k (r_k - \lambda) x_k \right)$$
(15)

We now proceed to the development of an efficient upper bound for function (15) at each node t. These bounds are tight enough to enable efficient pruning, and tractable enough to

be quickly computed despite the high non-linearity of the objective (15). For the case where $C_1^t > 0$, we derive the following bound.

Proposition 6. An upper bound of $f_t(x)$ in (15) if $C_1^t > 0$, is

$$f_t(x) \leqslant (V_1^t)^{\gamma - 1} C_1^t e^{z_1^*(t)}$$
 (16)

where

$$z_1^*(t) = \sum_{k \in \bar{K}} v_k \max\left(0, \frac{2(\gamma - 1)}{2V_1^t + \sum_{k \in \bar{K}^t} v_k} + \frac{(r_k - \lambda)}{C_1^t}\right)$$

Proof. See Appendix.

Preliminary numerical experiments enabled to show that using this bound improves the computation time of the Branch-and-Bound algorithm.

3.3. Possibly synergistic products ($\gamma > 1$)

In this section, we analyze the properties of subproblem (10) when the dissimilarity parameter of a nest is higher than one. These properties enable again to fix variables without further calculation. We summarize these properties in the preprocessing phase. The structure of the B&B tree depending heavily on the characteristics of the root node, again we first introduce the preprocessing at the root node.

Proposition 7. Define $\mathcal{H} = \sum_{k \in K: r_k \geqslant \lambda} v_k(r_k - \lambda) - \lambda v_0$. Depending on the value of \mathcal{H} , we can have one of the following scenarios:

i) if $\mathcal{H}=0$ (Case 0), then defining $K_1^0=\{k\in N:r_k\geqslant \lambda\}$ and $K_0^0=\{k\in N\setminus K_1^0:r_k<\lambda\}$, we have $x_k^*=1$ for $k\in K_1^0$ and $x_k^*=0$ for $k\in K_0^0$, and the subproblem is solved without branching.

ii) if
$$\mathcal{H} > 0$$
 (Case 1), we define $K_1^0 = \{k \in N : r_k \geqslant \lambda\}$. Then $x_k^* = 1$ for $k \in K_1^0$. In addition, set $K_0^0 = \{k \in N \setminus K_1^0 : r_k < \lambda - (\gamma - 1)(C_1^0/V_1^0)\}$. Then $x_k^* = 0$ for $k \in K_0^0$.

iii) if $\mathcal{H}<0$ (Case 2), define $K_0^0=\{k\in N: r_k<\lambda\}$. Then $x_k^*=0$ for $k\in K_0^0$.

Proof. See Appendix.
$$\Box$$

Proposition 8. If $\mathcal{H} > 0$, at any node $t \neq 0$, $x_k^* = 0$ for $k \in K_0^t$, where $K_0^t = \{k \in \bar{K}^{t-1} : r_k < \lambda - (\gamma - 1)(C_1^t/V_1^t)\}.$

Proof. See Appendix.

We note then the objective function after preprocessing at node t:

$$\max_{x \in \{0,1\}^{|\bar{K}^t|}} f^t(x) = \left(V_1^t + \sum_{k \in \bar{K}^t} v_k x_k \right)^{\gamma - 1} \times \left(C_1^t + \sum_{k \in \bar{K}^t} v_k (r_k - \lambda) x_k \right)$$
(17)

We now design an upper bound for pruning nodes in the case where $\gamma > 1$ and $C_1^t > 0$.

Proposition 9. An upper bound of $f_t(x)$ in (17) when $C_1^t > 0$ is

$$f_t(x) \leqslant (V_1^t)^{\gamma - 1} C_1^t e^{z_2^*(t)}$$

where

$$z_2^*(t) = \sum_{k \in \bar{K}} v_k \max\left(0, \frac{\gamma - 1}{V_1^t} + \frac{r_k - \lambda}{C_1^t}\right)$$

Proof. See Appendix.

The above upper bound can be computed in linear time $O(|\bar{K}^t|)$, if revenues r_k are already sorted in a pre-processing phase.

4. Numerical experiments

In this section, we analyze the results of an extensive set of computational experiments drawn to evaluate the performance of our tailored branch-and-bound embedded in the fractional programming framework (denoted by FP+BB) compared to the state-of-the-art heuristic proposed by Davis et al. [9], denoted by Heuristic. All the experiments have been carried out on a virtual machine with an Intel(R) Core i7-3770 CPU, a 3.4 GHz processor with 8GB of RAM using a 64-bit Windows operating system. The code was written and run using Julia v0.6.4.

4.1. Experimental setup

We divide our computational experiments into three main groups based on the number of products available. For the first group, we solve instances of the AOPNL with m = 5 and n = 10. We compute the maximum expected revenue by offering sorted-by-revenue assortments in each nest (Heuristic method of Davis et al. [9]) and using FP+BB. ¹. For

¹In the pretests, we also used Couenne, an open source branch & bound algorithm for solving MINLPs, however, due to numerical issues, we were not able to find the optimal solution for many instances and excluded the use of Couenne from our experiments.

fractional programming, we tested both solving the parameterized subproblem by our tailored branch-and-bound algorithm (FP+BB), and by full enumeration of all possible assortments denoted by (FP+F.Enum.) which was possible only very small problem instances.

As for the second group, we solve instances with m = 5 and $n \in \{25, 50, 100, 250\}$. In this case, we excluded full enumeration of all assortments for the subproblem because of combinatorial explosion. Finally, for the last group with super large instances, we solve instances with m = 5 and $n \in \{500, 1000, 5000\}$.

To generate the value of preferences v_{ik} and revenues r_{ik} , we follow a similar procedure as in Gallego and Topaloglu [15]. Recall that index i identifies a nest and index k identifies a product. We randomly generate values U_{ik} using a uniform distribution in the interval [0, 1]. We then randomly generate values X_{ik} and Y_{ik} with a uniform distribution in [50, 300] and use these values to generate revenues and preferences as follow: $r_{ik} = 10 \times U_{ik}^2 \times X_{ik}$, $v_{ik} = 10 \times (1 - U_{ik}) \times Y_{ik}$. Using U_{ik} , products with larger revenues are more likely to have smaller preference weights, which means that more expensive products are usually less attractive. However, X_{ik} and Y_{ik} add some noise so that not always products that are more expensive have low attractiveness. The square power in U_{ik}^2 skews the distribution of revenues in order to have a large number of products with small revenues and a small number of products with large revenues ([15, 13]).

To generate the value of $\gamma_i, \forall i \in M$, we use a uniform distribution in $[\gamma^L, \gamma^U]$ with the same intervals [0.5, 1.5], [1, 2], [1.5, 2.5] and [2, 3] as in [9]. We set $V_0 = 30$ and for a thorough analysis, for each value of n, we consider three cases where $v_{i0} = 0, \forall i \in M, v_{i0} = 30, \forall i \in M$ and finally $v_{i0} = 0$ for some $i \in M$, and $v_{i0} = 30$ for some $i \in M$.

For our FP+BB method, we record the overall number of iterations. We also set a time limit of 3,600 seconds for each instance. If FP+BB does not converge to optimality within the time limit, we report the value of the best found assortment ($\Pi(S_{best})$ from Algorithm 1). In the latter case, we also calculate the last value of λ_u obtained during the parametric search, as a valid upper bound on the optimal assortment.

4.2. Computational results

We provide the results of our computational experiments in Tables 2–7. Recall that we solve problems with a number of products ranging from n=10 to n=5000. We report the results of the experiments corresponding to every value of n in a separate table. In all tables, the first column determines the combination of parameters v_{i0} and γ_i . We also consider various intervals for the generation of dissimilarity parameter which we show by $[\gamma^L, \gamma^U]$. To better observe the impact of v_{i0} on the performance of the FP+BB, we consider separate groups of instances. In all tables we solve instances of the AOPNL by offering the best sorted-by-revenue assortments in each nest by solving the linear problem expressed through formulation (7)–(9) and using FP+BB. We report the CPU time in seconds of each method (Time) along with the best expected revenue (Obj.) found by each method. Recall that for each combination

of parameters (each row), we solve 20 instances. For each problem instance, the average percentage of improvement in the expected revenue that can be made by using our FP+BB is determined as:

Impr.(%) =
$$\frac{1}{|\mathcal{P}|} \sum_{p \in \mathcal{P}} 100 \times \left(\frac{\text{BEST}^p - \text{HEUR}^p}{\text{HEUR}^p} \right)$$

where p denotes a single problem instances in \mathcal{P} that is the set of instances and HEUR^p is the expected revenue obtained by offering sorted-by-revenue assortments for instance $p \in \mathcal{P}$ and finally, we use BEST^p to denote the optimal expected revenue found by FP+BB (or $\Pi(S_{best})$, if it reaches the time limit). This gap can also be interpreted as the average improvement in revenue obtained by FP+BB. We use Impr.(%) to demonstrate this value in the tables.

For the FP+BB method, we also report: the number of instances (out of 20) for which the optimal solution was found (# Opt); the overall number of instances (out of 20) for which FP+BB has improved the expected revenue found by Heuristic, and the average number of iterations of the FP+BB approach. Finally, for the FP+F.Enum. method we report the average CPU time in seconds (Time).

In Table 2, we report the results for instances with n = 10. As these instances are small, we are able to determine the optimal solution for the subproblem (10) and consequently, for the original AOPNL (2), by generating all 2^n possible assortments for each nest. As a result, in Table 2, we report the CPU time of the FP+F.Enum. method used to generate all possible assortments when solving the subproblem, instead of using the specialized branch-and-bound.

Results in this table show that our FP+BB method performs well in terms of finding the optimal solution with a processing time almost equal to the heuristic of [9]. We can also observe that the heuristic exhibits significant gaps with respect to the optimal solution. As expected, regardless of the value of v_{i0} , the overall trend is that the performance of FP+BB improves as the values in $[\gamma^L, \gamma^U]$ increase. We can also observe that in general and regardless of the value of v_{i0} , if all $\gamma_i > 1$, the performance of the heuristic method degrades compared to the case where some $\gamma_i \leq 1$. For example, if we shift from $[\gamma^L, \gamma^U] = [0.5, 1.5]$ to $[\gamma^L, \gamma^U] = [1, 2]$, using the fractional programming approach we will get an average revenue improvement of 23% if $v_{i0} = 0, \forall i \in M$. We also expected that using full enumeration is computationally much costlier than following our proposed B&B – the FP+F.Enum. is an order of magnitude slower than FP+BB for the smallest instances with n = 10, but already for n = 25 the full enumeration approach was intractable.

In Tables 3–6, we give our main results obtained by solving instances with $n \in \{25, 50, 100, 250\}$. The main observation is that as long as $v_{i0} = 0, \forall i \in M$, we are able to obtain the optimal solution using our tailored B&B in less than 0.3 second and with a relatively significant improvement in the expected revenue. Same as before, as the value of $[\gamma^L, \gamma^U]$ increases, the

expected revenue improvement realized by using the B&B increases and the performance of the sorted-by-revenue assortments degrades. This is the general pattern in all the tables regardless of the value of v_{i0} and the number of products. Another observation is that when $v_{i0} > 0$ even for some nests, the parametric search can sometimes reach the time limit. However, the resulting FP+BB solution still provides a sizable improvement in the expected revenue as seen in the fourth and eighth columns in Tables 3–6.

As can be expected, with an increase in the number of products, the time required for the parametric search to converge to the optimal solution also increases. Such increase is more drastic if all or even some of the v_{i0} have non-zero values and if $\gamma_i \leq 1$ for some nests. As result, in Table 6, we observe that unless $\gamma_i > 1$ or $v_{i0} = 0$, $\forall i \in M$, the search process of the proposed FP+BB reaches the time limit; however, even in that case, using FP+BB provides an improvement in the expected revenue over the Heuristic solution. Recall that for each combination of parameters, we solve 20 instances, and for the instances where FP+BB does not converge to the optimal solution before the time limit is reached, we record the valid upper bound λ_u . In that case, we report in Table 6 the duality gap, denoted by Gap(%), which is calculated as:

$$\operatorname{Gap}(\%) = \frac{1}{|\mathcal{G}|} \sum_{g \in \mathcal{G}} 100 \times \left(\frac{\lambda_u^g - \operatorname{BEST}^g}{\lambda_u^g} \right)$$

where $g \in \mathcal{G}$ is a single instance where FP+BB search stopped at time limit and $|\mathcal{G}|$ is the total number of those instances. Finally, λ_u^g is the final upper bound on λ before the time limit is reached.

While some of the important improvements depend on the interval $[\gamma^L, \gamma^U]$, we observe that in general, as the number of products increases, the overall improvement achieved by FP+BB decreases. Finally, after an extensive experimentation, we found out that if all $v_{i0} = 0$, the processing time for reaching optimality does not significantly grow with a large increase in the number of products. For that reason, we devised several instances with super large sizes and report our main findings in Table 7. As we can see in Table 7, even with n = 500 and n = 1,000, FP+BB is able to find the optimal assortment in less than 2 seconds. As for instances with n = 5,000 products, we observe that the CPU time increases before the search converges to the best solution, however, the optimal solution is still found in around 70 seconds on average.

We conclude this section by summarizing the results of the numerical analysis in two plots shown in Figures 1 and 2 for small and large instances and super large instances. In both plots, the horizontal axis shows the interval of the dissimilarity parameter of nests. We observe that with an increase in the value of the dissimilarity parameter, the overall improvement of FP+BB over the value found by Heuristic consistently increases, regardless of the value of v_{i0} or the number of products within each nest. Finding the optimal assortment by using our proposed FP+BB can improve the expected revenue by up to 63% compared to offering sorted-by-revenue assortments (Heuristic).

Table 2: Results on instances with n = 10

$v_{i0} = 0, \forall i \in M$	Heu	ristic			FP	+ BB			FP + F.Enum.	
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.	Time	
$\overline{[0.5, 1.5]}$	0.30	1319.412	0.35	1455.784	20	5	17.09	4.3	0.65	
[1, 2]	0.01	1499.060	0.02	2056.390	20	20	39.38	4.5	0.35	
[1.5, 2.5]	0.02	1464.430	0.02	2278.883	20	20	63.66	6.9	0.53	
$[2, \ 3]$	0.02	1470.562	0.02	2215.229	20	20	60.01	9.8	0.75	
$v_{i0} > 0, \forall i \in M$	Heu	ristic		FP + BB						
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.	Time	
[0.5, 1.5]	0.01	1363.523	0.02	1420.608	20	19	4.75	10.9	0.85	
[1, 2]	0.01	1372.336	0.02	1552.196	20	20	15.26	5.2	0.39	
[1.5, 2.5]	0.01	1290.883	0.02	1542.003	20	20	25.08	6.7	0.50	
[2, 3]	0.01	1484.537	0.02	1764.358	20	20	22.74	5.5	0.41	
$v_{i0} \geqslant 0, \forall i \in M$	Heu	ristic		FP + BB						
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.	Time	
[0.5, 1.5]	0.01	1420.262	0.02	1542.811	20	12	10.06	6.8	0.51	
[1, 2]	0.01	1602.591	0.02	1891.330	20	20	24.22	4.1	0.31	
[1.5, 2.5]	0.01	1406.567	0.03	1801.331	20	20	31.24	5.8	0.45	
$[2, \ 3]$	0.01	1466.853	0.02	1947.478	20	20	40.16	4.9	0.38	

Table 3: Results on instances with n=25

$v_{i0} = 0, \forall i \in M$	Heu	ristic		FP + BB						
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.		
[0.5, 1.5]	0.25	2011.361	0.29	2038.585	20	3	1.30	3.9		
[1, 2]	0.02	1874.942	0.02	2278.074	20	20	24.55	5.1		
[1.5, 2.5]	0.02	1941.861	0.02	2432.010	20	20	27.50	5.2		
$[2, \ 3]$	0.02	1881.559	0.02	2493.864	20	20	33.64	8.1		
$v_{i0} > 0, \forall i \in M$	Heuristic			FP + BB						
γ^L, γ^U	Time	Obj.	Time	Obj.	# Opt.	# Imp.	$\mathrm{Impr.}(\%)$	# Iter.		
[0.5, 1.5]	0.02	1631.454	0.05	1673.522	20	17	2.63	15.2		
[1, 2]	0.02	1699.821	0.03	1810.193	20	20	8.01	6.2		
[1.5, 2.5]	0.02	1743.259	0.03	1845.962	20	20	5.99	6.0		
$[2, \ 3]$	0.02	1769.376	0.03	1960.964	20	20	12.03	5.4		
$v_{i0} \geqslant 0, \forall i \in M$	Н	euristic				FP + BB				
$[\gamma^L,\gamma^U]$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	$\mathrm{Impr.}(\%)$	# Iter.		
[0.5, 1.5]	0.02	1772.294	0.04	1814.347	20	11	3.04	14.4		
[1, 2]	0.02	1820.927	0.02	1965.316	20	20	8.28	5.2		
[1.5, 2.5]	0.02	1826.060	0.02	2078.122	20	20	15.27	4.9		
$[2, \ 3]$	0.02	1827.334	0.02	2106.624	20	20	16.90	4.8		

Table 4: Results on instances with n = 50

$v_{i0} = 0, \forall i \in M$	Н	euristic				FP + BB		
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.
[0.5, 1.5]	0.02	2102.011	0.03	2154.903	20	4	2.74	6.8
[1, 2]	0.03	2271.554	0.03	2439.062	20	20	7.90	4.2
[1.5, 2.5]	0.02	2318.757	0.02	2572.765	20	20	11.35	5.0
[2, 3]	0.02	2195.411	0.02	2579.245	20	20	18.30	6.1
$v_{i0} > 0, \forall i \in M$	Н	euristic				FP + BB		
$[\gamma^L,\gamma^U]$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	$\mathrm{Impr.}(\%)$	# Iter.
[0.5, 1.5]	0.02	1859.730	0.24	1870.572	20	15	0.56	22.6
[1, 2]	0.02	1932.296	0.04	1957.362	20	19	1.34	8.6
[1.5, 2.5]	0.02	1968.766	0.03	2014.973	20	20	2.51	6.2
$[2, \ 3]$	0.02	1945.271	0.04	2022.854	20	20	4.10	6.5
$v_{i0} \geqslant 0, \forall i \in M$	Н	euristic				FP + BB		
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.
[0.5, 1.5]	0.02	2055.472	0.26	2067.200	20	12	0.61	20.3
[1, 2]	0.02	2037.008	0.04	2137.010	20	20	5.03	7.5
[1.5, 2.5]	0.02	2113.793	0.03	2204.823	20	20	4.32	5.5
[2, 3]	0.02	2144.774	0.04	2279.204	20	20	6.80	5.7

Table 5: Results on instances with n = 100

$v_{i0}=0, \forall i \in M$	Н	euristic				FP + BB		
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.
[0.5, 1.5]	0.03	2347.244	0.04	2363.281	20	9	0.72	8.0
[1, 2]	0.03	2449.480	0.04	2542.060	20	18	3.98	8.1
[1.5, 2.5]	0.03	2393.254	0.07	2623.670	20	20	9.92	5.5
[2, 3]	0.03	2459.432	0.04	2669.409	20	20	8.66	5.8
$v_{i0} > 0, \forall i \in M$	Heuristic					FP + BB		
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	$\mathrm{Impr.}(\%)$	# Iter.
[0.5, 1.5]	0.03	2040.691	2.40	2042.736	20	9	0.10	35.0
[1, 2]	0.03	2074.101	0.11	2087.427	20	18	0.66	11.6
[1.5, 2.5]	0.03	2095.977	0.07	2122.436	20	20	1.26	7.0
[2, 3]	0.03	2099.439	0.07	2141.169	20	20	2.09	7.0
$v_{i0} \geqslant 0, \forall i \in M$	Н	euristic				FP + BB		
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.
[0.5, 1.5]	0.03	2020.733	3.16	2026.195	20	11	0.26	25.8
[1, 2]	0.03	2084.302	0.10	2095.638	20	19	0.54	12.9
[1.5, 2.5]	0.03	2105.198	0.06	2127.319	20	20	1.05	6.8
[2, 3]	0.03	2114.391	0.08	2144.870	20	20	1.49	7.7

Table 6: Results on instances with n=250

$v_{i0} = 0, \forall i \in M$	Heu	ristic				FP + BB			
$[\gamma^L, \gamma^U]$	Time	Obj.	Time	Obj.	# Opt.	$\mathrm{Gap}(\%)$	# Imp.	$\mathrm{Impr.}(\%)$	# Iter.
[0.5, 1.5]	0.05	2467.701	0.22	2479.887	20	0.00	6	0.53	22.9
[1, 2]	0.05	2618.941	0.08	2656.178	20	0.00	19	1.44	7.6
[1.5, 2.5]	0.05	2629.566	0.08	2721.555	20	0.00	20	3.58	5.2
$[2, \ 3]$	0.05	2630.360	0.08	2749.843	20	0.00	20	4.60	5.5
$v_{i0} = 0, \forall i \in M$	Heuristic					FP + BB			
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	$\operatorname{Gap}(\%)$	# Imp.	$\mathrm{Impr.}(\%)$	# Iter.
[0.5, 1.5]	0.06	2203.200	1855.32	2203.200	11	7.72	5	0.00	22.9
[1, 2]	0.05	2240.957	0.60	2246.826	20	0.00	17	0.27	14.8
[1.5, 2.5]	0.05	2251.769	0.31	2268.824	20	0.00	20	0.76	8.4
$[2, \ 3]$	0.05	2301.263	0.34	2315.573	20	0.00	20	0.62	7.1
$v_{i0} = 0, \forall i \in M$	Heu	ristic				FP + BB			
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	Gap(%)	# Imp.	Impr.(%)	# Iter.
[0.5, 1.5]	0.06	2245.679	1463.56	2245.960	13	2.58	5	0.01	23.1
[1, 2]	0.06	2254.461	0.58	2262.545	20	0.00	16	0.35	15.0
[1.5, 2.5]	0.05	2359.736	0.83	2385.752	20	0.00	20	1.13	6.7
$[2, \ 3]$	0.05	2360.125	0.75	2403.292	20	0.00	20	1.86	6.2

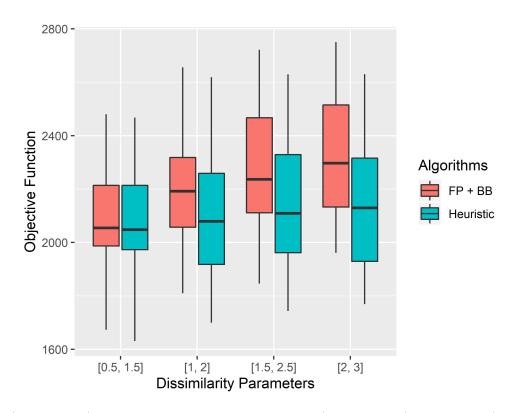


Figure 1: (Color online) Expected revenues found by optimal (or best found) assortments (FP+BB) versus Heuristic, for a set of small and large instances $(n \in \{25, 50, 100, 250\})$

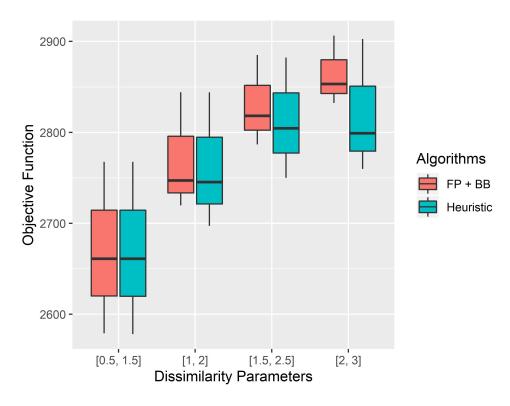


Figure 2: (Color online) Expected revenues found by optimal assortments (FP+BB) versus Heuristic, for a set of super large instances $(n \in \{500, 1000, 5000\})$

Table 7: Results on super large instances with $v_{i0} = 0, \forall i \in M$

n = 500	Heu	Heuristic			FP	+ BB				
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.		
$\overline{[0.5, 1.5]}$	0.10	2578.208	0.49	2579.121	20	5	0.03	26.3		
[1, 2]	0.11	2697.146	0.22	2719.671	20	20	0.84	9.2		
[1.5, 2.5]	0.10	2749.865	0.18	2786.700	20	19	1.36	6.3		
$[2, \ 3]$	0.11	2759.730	0.16	2832.230	20	20	2.67	5.2		
n = 1,000	Heuristic			FP + BB						
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	$\mathrm{Impr.}(\%)$	# Iter.		
[0.5, 1.5]	0.21	2661.075	1.49	2661.075	20	2	0.00	35.0		
[1, 2]	0.21	2745.328	1.07	2747.184	20	10	0.07	28.2		
[1.5, 2.5]	0.22	2804.493	0.81	2818.214	20	17	0.49	13.7		
$[2, \ 3]$	0.22	2799.017	0.35	2853.180	20	20	1.96	5.6		
n = 5,000	Heu	ristic			FP	+ BB				
$\overline{[\gamma^L,\gamma^U]}$	Time	Obj.	Time	Obj.	# Opt.	# Imp.	Impr.(%)	# Iter.		
[0.5, 1.5]	2.14	2767.521	14.17	2767.523	20	7	0.00	36.7		
[1, 2]	2.12	2843.984	70.97	2844.074	20	9	0.00	30.6		
[1.5, 2.5]	2.04	2882.258	10.53	2885.153	20	15	0.10	15.5		
[2, 3]	1.98	2902.711	14.23	2906.345	20	20	0.13	10.2		

5. Conclusion

In this paper, we studied an assortment problem in which customer choice behavior is modeled using a nested logit model. We proposed a first exact method that enables to find an optimal assortment regardless of the value of the dissimilarity parameter or the attractiveness of the no-purchase option within a nest, i.e. any mix of the values of these parameters can be handled by the algorithm. Our method is based on a parametric search approach in which we reformulated the problem as a fractional program and benefited from a nice property that the parameterized subproblem is decomposable by nests. We showed that the derived subproblem is NP-hard if a nest contains synergistic products. We developed a branch-and-bound algorithm that benefited from the structure of the subproblem by fixing many variables in a preprocessing phase. For the remaining variables, we developed efficient upper bounds in order to prune nodes.

We finally tested and compared the performance of our method against the state-of-the art heuristic with a performance guarantee. We considered various sets of instances with up to $5{,}000$ products per nest. Computational results revealed that by finding the optimal assortment, we were able to improve the values found by the heuristic up to 63% in problems with a small number of products, and up to 10% in problems with a large number of products.

An exciting direction for future research could be to modify our proposed method to solve problems with capacity or cardinality constraints. An AOPNL with both capacity and cardinality constraint for each particular nest in which all dissimilarity parameters are at most one has been studied in [15]. Developing an efficient exact method for a more general case in which some dissimilarity parameters are higher than one remains open.

References

- [1] C. Archetti, G. Desaulniers, and M. G. Speranza. Minimizing the logistic ratio in the inventory routing problem. *EURO Journal on Transportation and Logistics*, 6(4):289–306, 2017.
- [2] M. E. Ben-Akiva, S. R. Lerman, and S. R. Lerman. *Discrete choice analysis: theory and application to travel demand*, volume 9. MIT press, 1985.
- [3] D. Bertsimas and P. Vayanos. Data-driven learning in dynamic pricing using adaptive optimization. *Preprint*, 2015.
- [4] A. Billionnet. Optimal selection of forest patches using integer and fractional programming. Operational Research An International Journal, 10:1–26, 2010.
- [5] A. Billionnet. Mathematical optimization ideas for biodiversity conservation. European Journal of Operational Research, 231(3):514 -534, 2013.
- [6] A. Börsch-Supan. On the compatibility of nested logit models with utility maximization. Journal of Econometrics, 43(3):373–388, 1990.
- [7] O. Çetin, A. J. Mersereau, and A. K. Parlaktürk. Management and effects of in-store promotional displays. *Manufacturing & Service Operations Management*, 2019.
- [8] R. Chen and H. Jiang. Capacitated assortment and price optimization under the multilevel nested logit model. *Operations Research Letters*, 47(1):30–35, 2019.
- [9] J. M. Davis, G. Gallego, and H. Topaloglu. Assortment optimization under variants of the nested logit model. *Operations Research*, 62(2):250–273, 2014.
- [10] J. M. Davis, H. Topaloglu, and D. P. Williamson. Pricing problems under the nested logit model with a quality consistency constraint. *INFORMS Journal on Computing*, 29 (1):54–76, 2016.
- [11] A. Désir, V. Goyal, and J. Zhang. Near-optimal algorithms for capacity constrained assortment optimization. Submitted to Operations Research, Available at SSRN 2543309, 2014.
- [12] W. Dinkelbach. On nonlinear fractional programming. *Management science*, 13(7): 492–498, 1967.
- [13] J. B. Feldman and H. Topaloglu. Capacity constraints across nests in assortment optimization under the nested logit model. *Operations Research*, 63(4):812–822, 2015.
- [14] A. Flores, G. Berbeglia, and P. Van Hentenryck. Assortment optimization under the sequential multinomial logit model. *European Journal of Operational Research*, 273(3): 1052–1064, 2019.
- [15] G. Gallego and H. Topaloglu. Constrained assortment optimization for the nested logit model. *Management Science*, 60(10):2583–2601, 2014.

- [16] V. Goyal, R. Levi, and D. Segev. Near-optimal algorithms for the assortment planning problem under dynamic substitution and stochastic demand. *Operations Research*, 64(1): 219–235, 2016.
- [17] G. W. Klau, I. Ljubić, P. Mutzel, U. Pferschy, and R. Weiskircher. The fractional prize-collecting steiner tree problem on trees. In G. Di Battista and U. Zwick, editors, *Algorithms ESA 2003*, pages 691–702, Berlin, Heidelberg, 2003. Springer Berlin Heidelberg. ISBN 978-3-540-39658-1.
- [18] A. G. Kök, M. L. Fisher, and R. Vaidyanathan. Assortment planning: Review of literature and industry practice. In *Retail supply chain management*, pages 99–153. Springer, 2008.
- [19] G. Li and P. Rusmevichientong. A greedy algorithm for the two-level nested logit model. Operations Research Letters, 42(5):319–324, 2014.
- [20] G. Li, P. Rusmevichientong, and H. Topaloglu. The d-level nested logit model: Assortment and price optimization problems. *Operations Research*, 63(2):325–342, 2015.
- [21] D. McFadden. Econometric models for probabilistic choice among products. *Journal of Business*, pages S13–S29, 1980.
- [22] D. McFadden et al. Conditional logit analysis of qualitative choice behavior. Frontiers in Econometrics, ed. by P. Zarembka, New York: Academic Press, pages 105–142, 1973.
- [23] N. Megiddo. Combinatorial optimization with rational objective functions. In *Proceedings* of the tenth annual ACM symposium on Theory of computing, pages 1–12. ACM, 1978.
- [24] P. Rusmevichientong and H. Topaloglu. Robust assortment optimization in revenue management under the multinomial logit choice model. *Operations Research*, 60(4): 865–882, 2012.
- [25] D. Segev. Assortment planning with nested preferences: Dynamic programming with distributions as states? *Algorithmica*, 81(1):393–417, 2019.
- [26] S. Sethuraman and S. Butenko. The maximum ratio clique problem. *Computational Management Science*, 12:197–218, 2015.
- [27] K. Talluri and G. Van Ryzin. Revenue management under a general discrete choice model of consumer behavior. *Management Science*, 50(1):15–33, 2004.
- [28] H. C. Williams. On the formation of travel demand models and economic evaluation measures of user benefit. *Environment and planning A*, 9(3):285–344, 1977.

Appendix A.

Proof of Proposition 2. Since the parameterized problem has a piece-wise linear structure, each piece of line corresponding to an i has a unique slope. On the other hand, all assortments corresponding to that piece of line are equal. As a result, if $S_l(\lambda_l) = S_u(\lambda_u)$, it means that both

 $S_l(\lambda_l)$ and $S_u(\lambda_u)$ belong to the same piece of line and since $F_{par}(\lambda_l) > 0$ and $F_{par}(\lambda_u) < 0$, therefore, $S_l(\lambda_l) = S_u(\lambda_u)$, then $S^* = S_l(\lambda_l) = S_u(\lambda_u)$.

Proof of Proposition 4.

- i) if $\mathcal{H} = 0$, it means that by adding all the products whose revenue is greater than or equal to λ , the second part on the right-hand-side of the objective function (10) will be zero and therefore, the value of the function (10) will be zero. This means that the lower bound is zero and removing any of these products will result in a negative value of the objective function therefore $x_k = 1$ for $k \in K_1^0$ where $K_1^0 = \{k \in K : r_k \geqslant \lambda\}$. On the other hand, since the lower bound is zero, adding a product with $r_k < \lambda$ will turn the second part of the right-hand-side of the objective function (10) negative, which in turn results in a negative value. Therefore, $x_k^* = 0$ for $k \in K_0^0 = \{k \in K \setminus K_1^0 : r_k < \lambda\}$.
- ii) if $\mathcal{H} > 0$, then there exists a subset of products with $r_k \geqslant \lambda$ that if offered in the assortment of nest i, so the value of the objective function (14) will be positive. As a result, offering any product from $K_0^0 = \{k \in K : r_k < \lambda\}$ will reduce the numerator of the formulation (14) and at the same time increase the value of its denominator which in turn decreases the value of the fraction. Therefore, $x_k^* = 0$ for $k \in K_0^0$. Now that we are left with only products with revenue $r_k > \lambda$, we define $K' = N \setminus K_0^0$, $r_{max} = \max_{j \in N} \{r_j\}$ and calculate the partial derivative of function (10). We have:

$$\begin{split} \frac{\partial f^0(x)}{\partial x_k} &= (\gamma - 1) \left(v_0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 2} v_k \left(\sum_{j \in K'} v_j (r_j - \lambda) x_j - \lambda v_0 \right) + \left(v_0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 1} v_k (r_k - \lambda) \\ &= v_k \left(v_0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \frac{\sum_{j \in K'} v_j (r_j - \lambda) x_j - \lambda v_0}{v_0 + \sum_{j \in K'} v_j x_j} + (r_k - \lambda) \right) \\ &= v_k \left(v_0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \frac{\sum_{j \in K'} v_j (r_j - \lambda) x_j - \lambda v_0 + v_0 (r_{max} - \lambda) - v_0 (r_{max} - \lambda)}{v_0 + \sum_{j \in K'} v_j x_j} \right. \\ &\quad + (r_k - \lambda) \right) \\ &\geqslant v_k \left(v_0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \frac{\left(r_{max} - \lambda \right) \sum_{j \in K'} v_j x_j + v_0 (r_{max} - \lambda) - \lambda v_0 - v_0 (r_{max} - \lambda)}{v_0 + \sum_{j \in K'} v_j x_j} \right. \\ &\quad + (r_k - \lambda) \right) \\ &\text{since} \qquad \gamma - 1 < 0 \\ &= v_k \left(v_0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left(\left(r_{max} - \lambda \right) - \frac{v_0 r_{max}}{v_0 + \sum_{j \in K'} v_j x_j} \right) + (r_k - \lambda) \right) \\ &\geqslant v_k \left(v_0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left(\left(r_{max} - \lambda \right) - \frac{v_0 r_{max}}{v_0 + \sum_{j \in K'} v_j x_j} \right) + (r_k - \lambda) \right) \\ &\text{since} \qquad r_{max} - \lambda > 0 \\ &\geqslant 0 \qquad \text{if} \qquad r_k \geqslant \lambda + (1 - \gamma) \left(r_{max} - \lambda - \frac{v_0 r_{max}}{v_0 + \sum_{j \in K'} v_j} \right) \end{split}$$

The function is increasing in x_k for $k \in K_1^0 = \{k \in N \setminus K_0^0 : r_k \geqslant \lambda + (1 - \gamma)(r_{max} - \lambda - (v_0 r_{max})/(v_0 + \sum_{j \in K'} v_j))\}$, then for these products k we have $x_k^* = 1$.

iii) if $\mathcal{H} < 0$, in this case, there exists no positive value for the objective function. In other words, for any vector x, $f^0(x) < 0$. In this case, since the value of the fraction on the right-hand-side of (14) is always negative, adding products with $r_k \ge \lambda$ will always make the numerator less negative and at the same time, increases the value of the denominator which in turn results in an overall less negative value of the objective function (14). Therefore, define $K_1^0 = \{k \in \mathbb{N} : r_k \ge \lambda\}$ then $x_k^* = 1, \forall k \in K_1^0$.

Defining $C_1^0 = \sum_{k \in K_1^0} v_k(r_k - \lambda) - \lambda v_0$, $V_1^0 = \sum_{k \in K_1^0} v_k + v_0$ and $K' = N \setminus K_1^0$, we can update

the objective function (10) with the remaining of the variables as:

$$\max_{x \in \{0,1\}^{|K'|}} f^0(x) = \left(V_1^0 + \sum_{k \in K'} v_k x_k\right)^{\gamma - 1} \times \left(C_1^0 + \sum_{k \in K'} v_k (r_k - \lambda) x_k\right)$$

We define $r_{min} = \min_{j \in K'} \{r_j\}$ and $\Delta = C_1^0 - V_1^0(r_{min} - \lambda)$, calculating the partial derivative of the function above with respect of variable x_k , we have:

$$\begin{split} \frac{\partial f^{0}(x)}{\partial x_{k}} &= (\gamma - 1) \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 2} v_{k} \left(C_{1}^{0} + \sum_{j \in K'} v_{j} (r_{j} - \lambda) x_{j} \right) + \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} v_{k} (r_{k} - \lambda) \\ &= v_{k} \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} \left((\gamma - 1) \frac{C_{1}^{0} + \sum_{j \in K'} v_{j} (r_{j} - \lambda) x_{j}}{V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j}} + (r_{k} - \lambda) \right) \\ &\leqslant v_{k} \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} \left((\gamma - 1) \frac{C_{1}^{0} + (r_{min} - \lambda) \sum_{j \in K'} v_{j} x_{j}}{V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j}} + (r_{k} - \lambda) \right) \\ &= v_{k} \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} \left((\gamma - 1) \frac{(r_{min} - \lambda) \sum_{j \in K'} v_{j} x_{j} + V_{1}^{0} (r_{min} - \lambda) + C_{1}^{0} - V_{1}^{0} (r_{min} - \lambda)}{V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j}} + (r_{k} - \lambda) \right) \\ &= v_{k} \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} \left((\gamma - 1) \left((r_{min} - \lambda) + \frac{C_{1}^{0} - V_{1}^{0} (r_{min} - \lambda)}{V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j}} \right) + (r_{k} - \lambda) \right) (\star) \end{split}$$

We now have two cases. If $\Delta \geqslant 0$, we can transform the expression denoted by (\star) as:

$$\leqslant v_k \left(V_1^0 + \sum_{j \in K'} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left((r_{min} - \lambda) + \frac{C_1^0 - V_1^0 \left(r_{min} - \lambda \right)}{V_1^0 + \sum_{j \in K'} v_j} \right) + (r_k - \lambda) \right)$$

$$\text{since} \quad \gamma - 1 < 0$$

$$\leqslant 0 \quad \text{if} \quad r_k \leqslant \lambda + (1 - \gamma) \left(\frac{C_1^0 + (r_{min} - \lambda) \sum\limits_{j \in K'} v_j}{V_1^0 + \sum\limits_{j \in K'} v_j} \right)$$

On the other hand, if $\Delta < 0$, we transform (\star) as follows:

Therefore, if $\Delta \geqslant 0$, $x_k^* = 0$ for $k \in K_0^0 = \{k \in K' : r_k \leqslant \lambda + (1 - \gamma) \left(\frac{C_1^0 + (r_{min} - \lambda) \sum_{j \in K'} v_j}{V_1^0 + \sum_{j \in K'} v_j}\right)$, and if $\Delta < 0$, then $x_k^* = 0$ for $k \in K_0^0 = \{k \in K' : r_k \leqslant \lambda + (1 - \gamma) \left(C_1^0 / V_1^0\right).$ \square Proof of Proposition 5.

i) We set $r_{max} = \max_{j \in \bar{K}^{t-1}} \{r_j\}$. Calculating the partial derivative of the function (13), we have:

$$\begin{split} \frac{\partial f^t(x)}{\partial x_k} &= (\gamma - 1) \left(V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j \right)^{\gamma - 2} v_k \left(C_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j (r_j - \lambda) x_j \right) \\ &+ \left(V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \frac{C_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j (r_j - \lambda) x_j}{V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j} + (r_k - \lambda) \right) \\ &= v_k \left(V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left(\frac{C_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j r_j - \lambda) x_j + V_1^{t-1} (r_{max} - \lambda)}{V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j} \right) \\ &= v_k \left(V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left(\frac{C_1^{t-1} + (r_{max} - \lambda) \sum_{j \in \tilde{K}^{t-1}} v_j x_j + V_1^{t-1} (r_{max} - \lambda)}{V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j} \right) \\ &= v_k \left(V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left(\frac{C_1^{t-1} + (r_{max} - \lambda) \sum_{j \in \tilde{K}^{t-1}} v_j x_j + V_1^{t-1} (r_{max} - \lambda)}{V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j} \right) \\ &= v_k \left(V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left((r_{max} - \lambda) + \frac{C_1^{t-1} - V_1^{t-1} (r_{max} - \lambda)}{V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j} \right) + (r_k - \lambda) \right) \\ &\geq v_k \left(V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j \right)^{\gamma - 1} \left((\gamma - 1) \left((r_{max} - \lambda) + \frac{C_1^{t-1} - V_1^{t-1} (r_{max} - \lambda)}{V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j x_j} \right) + (r_k - \lambda) \right) \\ &\geq 0 \quad \text{if} \quad r_k \geqslant \lambda + (1 - \gamma) \left(\frac{C_1^{t-1} + (r_{max} - \lambda) \sum_{j \in \tilde{K}^{t-1}} v_j}{V_1^{t-1} + \sum_{j \in \tilde{K}^{t-1}} v_j} \right) \right) \end{aligned}$$

Therefore, for $k \in K_1^t = \{k \in \bar{K}^{t-1} : r_k \geqslant \lambda + (1 - \gamma)(\frac{C_1^{t-1} + (r_{max} - \lambda)\sum_{j \in \bar{K}^{t-1}} v_j}{V_1^{t-1} + \sum_{j \in \bar{K}^{t-1}} v_j}), x_k^* = 1.$

ii) The proof of this section is similar to that section iii in the proof of Proposition 4. \Box Proof of Proposition 6. In this case, we can rewrite the objective function (15) as:

$$\begin{split} f^t(x) &= (V_1^t)^{\gamma-1}C_1^t \left(1 + \frac{\sum\limits_{k \in \tilde{K}^t} v_k x_k}{V_1^t}\right)^{\gamma-1} \times \left(1 + \frac{\sum\limits_{k \in \tilde{K}^t} v_k (r_k - \lambda) x_k}{C_1^t}\right) \\ &= (V_1^t)^{\gamma-1}C_1^t \exp\left(\ln\left(\left(1 + \frac{\sum\limits_{k \in \tilde{K}^t} v_k x_k}{V_1^t}\right)^{(\gamma-1)} \times \left(1 + \frac{\sum\limits_{k \in \tilde{K}^t} v_k (r_k - \lambda) x_k}{C_1^t}\right)\right)\right) \\ &= (V_1^t)^{\gamma-1}C_1^t \exp\left((\gamma - 1)\ln\left(1 + \frac{\sum\limits_{k \in \tilde{K}^t} v_k x_k}{V_1^t}\right) + \ln\left(1 + \frac{\sum\limits_{k \in \tilde{K}^t} v_k (r_k - \lambda) x_k}{C_1^t}\right)\right) \\ &\leqslant (V_1^t)^{\gamma-1}C_1^t \exp\left((\gamma - 1)\frac{2\sum\limits_{k \in \tilde{K}^t} v_k x_k}{2V_1^t + \sum\limits_{k \in \tilde{K}^t} v_k x_k} + \frac{\sum\limits_{k \in \tilde{K}^t} v_k (r_k - \lambda) x_k}{C_1^t}\right) \\ & \quad \sin \left(\frac{2\tau}{2 + \tau} \leqslant \ln(1 + \tau), \ln(1 + \tau) \leqslant \tau \text{ for } \tau \geqslant 0, r_k > \lambda, \forall k \in \tilde{K}^t \text{ and } \gamma - 1 < 0\right) \\ &\leqslant (V_1^t)^{\gamma-1}C_1^t \exp\left((\gamma - 1)\frac{2\sum\limits_{k \in \tilde{K}^t} v_k x_k}{2V_1^t + \sum\limits_{k \in \tilde{K}^t} v_k x_k} + \frac{\sum\limits_{k \in \tilde{K}^t} v_k (r_k - \lambda) x_k}{C_1^t}\right) \quad \text{since } \sum\limits_{k \in \tilde{K}^t} v_k x_k \leqslant \sum\limits_{k \in \tilde{K}^t} v_k \\ &= (V_1^t)^{\gamma-1}C_1^t \exp\left(\sum\limits_{k \in \tilde{K}^t} v_k \left(\frac{2(\gamma - 1)}{2V_1^t + \sum\limits_{k \in \tilde{K}^t} v_k} + \frac{(r_k - \lambda)}{C_1^t}\right) x_k\right) \end{split}$$

We note the coefficients inside the above exponential function as

$$w_k^t = v_k \left(\frac{2(\gamma - 1)}{2V_1^t + \sum\limits_{k \in \bar{K}^t} v_k} + \frac{(r_k - \lambda)}{C_1^t} \right)$$

Therefore, we get an upper bound on (15) by solving

$$\max_{x \in \{0,1\}^{|\bar{K}^t|}} \sum_{k \in \bar{K}^t} w_k^t x_k \tag{18}$$

Problem (18) is easily solved by offering all products with $w_k^t > 0$. Therefore, the solution of problem (18) is:

$$z_1^*(t) = \sum_{k \in \bar{K}^t} \max(0, w_k^t)$$

We finally obtain the upper bound on $f_t(x)$:

$$f_t(x) \leqslant (V_1^t)^{\gamma - 1} C_1^t e^{z_1^*(t)}$$

Proof of Proposition 7.

- i) the proof of this part is similar to that of Proposition 4.
- ii) The first part holds because for any S where $k \notin S$, the objective of $S \cup \{k\}$ is larger than that of S if $r_k \lambda \geqslant 0$. We can then include in the assortment all variables k such that $r_k \geqslant \lambda$. We also calculate $V_1^t = \sum_{k \in K_1^t} v_k + v_0$ and $C_1^t = \sum_{k \in K_1^t} v_k (r_k \lambda) \lambda v_0$ and define $K' = N \setminus K_1^0$. The subproblem then can be expressed as:

$$\max_{x \in \{0,1\}^{|K'|}} f^0(x) = \left(V_1^0 + \sum_{k \in K'} v_k x_k\right)^{\gamma - 1} \times \left(C_1^0 + \sum_{k \in K'} v_k (r_k - \lambda) x_k\right)$$
(19)

We compute the partial derivative of f in above function with respect to variable x_k :

$$\frac{\partial f^{0}(x)}{\partial x_{k}} = (\gamma - 1) \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 2} v_{k} \left(C_{1}^{0} + \sum_{j \in K'} v_{j} (r_{j} - \lambda) x_{j} \right) + \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} v_{k} (r_{k} - \lambda)$$

$$= v_{k} \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} \left((\gamma - 1) \frac{C_{1}^{0} + \sum_{j \in K'} v_{j} (r_{j} - \lambda) x_{j}}{V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j}} + (r_{k} - \lambda) \right)$$

$$\leq v_{k} \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} \left((\gamma - 1) \frac{C_{1}^{0}}{V_{1}^{0}} + (r_{k} - \lambda) \right) \quad \text{as } \sum_{j \in K'} v_{j} (r_{j} - \lambda) < 0$$

$$= v_{k} \left(V_{1}^{0} + \sum_{j \in K'} v_{j} x_{j} \right)^{\gamma - 1} \left((\gamma - 1) (C_{1}^{0} / V_{1}^{0}) + (r_{k} - \lambda) \right)$$

$$\leq 0 \quad \text{if} \quad r_{k} \leq \lambda - (\gamma - 1) (C_{1}^{0} / V_{1}^{0})$$

Therefore, if we define $K_0^0 = \{k \in N \setminus K_1^0 : r_k < \lambda - (\gamma - 1)(C_1^0/V_1^0)\}$, then $x_k^* = 0$ for $k \in K_0^0$.

iii) if $\mathcal{H} < 0$, similar to the case when $\gamma \leq 1$, there exists no positive value for the objective function. Therefore, since the value of the objective function 10 is always negative, adding products with $r_k < \lambda$ will always result in a lower value.

Proof of Proposition 8. The proof of this proposition if similar to that of Proposition 7. \Box

Proof of Proposition 9. We start reformulating $f^t(x)$ as in the third equality of the proof of Proposition 6:

$$f^{t}(x) = (V_{1}^{t})^{\gamma-1}C_{1}^{t} \exp\left((\gamma - 1)\ln\left(1 + \frac{\sum\limits_{k \in \bar{K}^{t}} v_{k}x_{k}}{V_{1}^{t}}\right) + \ln\left(1 + \frac{\sum\limits_{k \in \bar{K}^{t}} v_{k}(r_{k} - \lambda)x_{k}}{C_{1}^{t}}\right)\right)$$

$$\leqslant (V_{1}^{t})^{\gamma-1}C_{1}^{t} \exp\left((\gamma - 1)\frac{\sum\limits_{k \in \bar{K}^{t}} v_{k}x_{k}}{V_{1}^{t}} + \frac{\sum\limits_{k \in \bar{K}^{t}} v_{k}(r_{k} - \lambda)x_{k}}{C_{1}^{t}}\right)$$

$$\text{as } \ln(1 + \tau) \leqslant \tau \text{ and } r_{k} \leqslant \lambda \text{ for } k \in \bar{K}$$

$$= (V_{1}^{t})^{\gamma-1}C_{1}^{t} \exp\left(\sum_{k \in \bar{K}^{t}} v_{k}\left(\frac{\gamma - 1}{V_{1}^{t}} + \frac{r_{k} - \lambda}{C_{1}^{t}}\right)x_{k}\right)$$

Let us note the coefficients inside the above exponential function as

$$w_k^t = v_k \left(\frac{\gamma - 1}{V_1^t} + \frac{r_k - \lambda}{C_1^t} \right)$$

At the root node (t = 0) and for $k \in \bar{K}$, $r_k \geqslant \lambda - (\gamma - 1)(C_1^t/V_1^t)$, then all coefficients w_k^0 are non-negative. However, at an arbitrary B&B node t, some k with $r_k - \lambda < 0$ might have been added in V_1^t in the previous child nodes. Hence, coefficients w_k^t can be positive or negative. Then the solution to

$$\max_{x \in \{0,1\}^{|\bar{K}^t|}} \sum_{k \in \bar{K}^t} w_k^t x_k$$

can be obtained by having

$$z_2^*(t) = \sum_{k \in \bar{K}^t} \max(0, w_k^t)$$

Finally, we obtain the upper bound on $f_t(x)$:

$$f_t(x) \leqslant (V_1^t)^{\gamma - 1} C_1^t e^{z_2^*(t)}$$

Appendix B.

We summarize the findings of this section in Algorithms (2) and (3).

Algorithm 2: Preprocessing for t = 0 when $\gamma \leq 1$

```
1 N \leftarrow \text{set of all products};
 2 \mathcal{H} \leftarrow \sum_{k \in N: r_k \geqslant \lambda} v_k(r_k - \lambda) - \lambda v_0;
3 if \mathcal{H} = 0 then // Case 0
             K_1^0 = \{k \in N : r_k \geqslant \lambda\} ;
            Fix x_k^* = 1 for k \in K_1^0;
  5
            K_0^0 = \{k \in N \setminus K_1^0 : r_k < \lambda\} ;
  6
            Fix x_k^* = 0 for k \in K_0^0;
  7
            Exit (subproblem is solved);
  8
      else if \mathcal{H} > 0 then// Case 1
 9
            K_0^0 = \{k \in N : r_k < \lambda\};
10
            x_k^* = 0 \text{ for } k \in K_0^0 ;
11
            r_{max} = \max_{j \in N} \{r_j\} ;

K' = N \setminus K_0^0 ;
12
13
            K_1^0 = \{k \in K' : r_k \ge \lambda + (1 - \gamma)(r_{max} - \lambda - (v_0 r_{max})/(v_0 + \sum_{j \in K'} v_j))\} ;
14
            x_k^*=1, \forall k \in K_1^0 ;
15
            Continue with upper bound (V_1^t)^{\gamma-1}C_1^t e^{z_1^*(t)};
16
      else if \mathcal{H} < 0 then // Case 2
17
            K_1^0 = \{ k \in N : r_k \geqslant \lambda \} ;
18
            x_k^* = 1, \forall k \in K_1^0 ; 
C_1^0 = \sum_{k \in K_1^0} v_k(r_k - \lambda) - \lambda v_0 ;
19
20
            V_1^0 = v_0 + \sum_{k \in K_1^0} v_k ;
21
            K' = N \setminus K_1^0;
22
            r_{min} = \min_{j \in K'} \{r_j\} ;
23
             \Delta = C_1^0 - V_1^0(r_{min} - \lambda);
\mathbf{24}
            if \Delta \geqslant 0 then
25
                   K_0^0 = \{k \in K' : r_k \leq \lambda + (1 - \gamma)((C_1^0 + (r_{min} - \lambda) \sum_{i \in K'} v_i) / (V_1^0 + \sum_{i \in K'} v_i))\};
26
            else if \Delta < 0 then
27
              K_0^0 = \{ k \in K' : r_k \leqslant \lambda + (1 - \gamma)(C_1^0/V_1^0) \} ;
28
             x_k^* = 0 \text{ for } k \in K_0^0 ;
29
            Continue with branching;
30
```

Algorithm 3: Preprocessing for node $t \neq 0$ when $\gamma \leq 1$

```
1 \bar{K}^{t-1} \leftarrow set of undecided variables until node t;
 2 K_1^{t-1} \leftarrow set of variables fixed to 1 until node t;
 3 \text{ if } \mathcal{H} > 0 \text{ then } // \text{ Case } 1
             r_{max} = \max_{j \in \bar{K}^{t-1}} \{r_j\} ;
             K_1^t = \{k \in \bar{K}^{t-1} : r_k \geqslant \lambda + (1-\gamma)((C_1^{t-1} + (r_{max} - \lambda) \sum_{j \in \bar{K}^{t-1}} v_j)(V_1^{t-1} + \sum_{j \in \bar{K}^{t-1}} v_j)) ;
             x_k^* = 1, \forall k \in K_1^t;
  6
             Continue with upper bound (V_1^t)^{\gamma-1}C_1^t e^{z_1^*(t)};
  7
     else if \mathcal{H} < 0 then // Case 2
            \begin{array}{l} C_1^{t-1} = \sum_{k \in K_1^{t-1}} v_k(r_k - \lambda) - \lambda v_0 ; \\ V_1^{t-1} = v_0 + \sum_{k \in K_1^{t-1}} v_k ; \end{array}
 9
10
             r_{min} = \min_{j \in \bar{K}^{t-1}} \{r_j\} ;
11
             \Delta = C_1^{t-1} - V_1^{t-1}(r_{min} - \lambda) ;
12
13
               | \hat{K_0^t} = \{ k \in \bar{K}^{t-1} : r_k \leqslant \lambda + (1 - \gamma)((C_1^{t-1} + (r_{min} - \lambda) \sum_{j \in \bar{K}^{t-1}} v_j) / (V_1^{t-1} + \sum_{j \in \bar{K}^{t-1}} v_j)) \} ; 
14
             else if \Delta < 0 then
15
              K_0^t = \{k \in \bar{K}^{t-1} : r_k \leqslant \lambda + (1 - \gamma)(C_1^{t-1}/V_1^{t-1})\};
16
             x_k^* = 0 \text{ for } k \in K_0^t;
17
             Continue with branching;
18
```

Algorithm 4: Preprocessing for t = 0 when $\gamma > 1$

```
1 N \leftarrow \text{set of all products};
 2 \mathcal{H} \leftarrow \sum_{k \in K: r_k \geqslant \lambda} v_k(r_k - \lambda) - \lambda v_0;
 \mathbf{3} if \mathcal{H} = 0 then // Case 0
            K_1^0 = \{k \in N : r_k \geqslant \lambda\} ;
            x_k^* = 1, \forall k \in K_1^0 ;
            K_0^0 = \{ k \in N \setminus K_1^0 : r_k < \lambda \} ;
  6
            x_k^* = 0, \forall k \in K_0^0;
  7
            Exit (subproblem is solved);
 9 else if \mathcal{H} > 0 then// Case 1
            K_1^0 = \{ k \in N : r_k \geqslant \lambda \} ;
10
            x_k^* = 1, \forall k \in K_1^0; 
C_1^0 = \sum_{k \in K_1^0} v_k(r_k - \lambda) - \lambda v_0;
11
12
            V_1^0 = v_0 + \sum_{k \in K_1^0} v_k;
13
            K_0^0 = \{ k \in N \setminus K_1^0 : r_k < \lambda - (\gamma - 1)(C_1^0/V_1^0) \} ;
14
            x_k^* = 0, \forall k \in K_0^0;
15
            Continue with upper bound (V_1^t)^{\gamma-1}C_1^te^{z_2^*(t)} ;
16
17 else if \mathcal{H} < 0 then // Case 2
            K_0^0 = \{ k \in N : r_k < \lambda \} ;
18
            x_k^* = 0, \forall k \in K_0^0 ;
19
            Continue with branching;
20
```

Algorithm 5: Preprocessing for $t \neq 0$ when $\gamma > 1$

```
1 \bar{K}^{t-1} \leftarrow set of undecided variables until node t;

2 K_1^t \leftarrow set of variables fixed to 1 until node t;

3 C_1^t \leftarrow \sum_{k \in K_1^t} v_k(r_k - \lambda) - \lambda v_0;

4 V_1^t \leftarrow v_0 + \sum_{k \in K_1^t} v_k;

5 if \mathcal{H} > 0 then

6 K_0^t = \{k \in \bar{K}^{t-1} : r_k < \lambda - (\gamma - 1)(C_1^t/V_1^t)\};

7 x_k^* = 0, \forall k \in K_0^t;

8 Continue with upper bound (V_1^t)^{\gamma-1}C_1^t e^{z_2^*(t)};
```



ESSEC Business School

3 avenue Bernard-Hirsch CS 50105 Cergy 95021 Cergy-Pontoise Cedex France Tel. +33 (0)1 34 43 30 00 www.essec.edu

ESSEC Executive Education

CNIT BP 230 92053 Paris-La Défense France Tel. +33 (0)1 46 92 49 00 www.executive-education.essec.edu

ESSEC Asia-Pacific

5 Nepal Park Singapore 139408 Tel. +65 6884 9780

www.essec.edu/asia

ESSEC | CPE Registration number 200511927D
Period of registration: 30 June 2017 - 29 June 2023
Committee of Private Education (CPE) is part of SkillsFuture Singapore (SSG)

ESSEC Africa

Plage des Nations - Golf City Route de Kénitra - Sidi Bouknadel (Rabat-Salé) Morocco Tel. +212 (0)5 37 82 40 00 www.essec.edu CONTACT RESEARCH CENTER

research@essec.edu





